

inp.1 Löb's Theorem

inc:inp:lob:
sec The Gödel sentence for a theory \mathbf{T} is a fixed point of $\neg\text{Prov}_T(x)$, i.e., a sentence γ such that

$$\mathbf{T} \vdash \neg\text{Prov}_T(\ulcorner \gamma \urcorner) \leftrightarrow \gamma.$$

It is not provable, because if $\mathbf{T} \vdash \gamma$, (a) by provability condition (1), $\mathbf{T} \vdash \text{Prov}_T(\ulcorner \gamma \urcorner)$, and (b) $\mathbf{T} \vdash \gamma$ together with $\mathbf{T} \vdash \neg\text{Prov}_T(\ulcorner \gamma \urcorner) \leftrightarrow \gamma$ gives $\mathbf{T} \vdash \neg\text{Prov}_T(\ulcorner \gamma \urcorner)$, and so \mathbf{T} would be inconsistent. Now it is natural to ask about the status of a fixed point of $\text{Prov}_T(x)$, i.e., a sentence δ such that

$$\mathbf{T} \vdash \text{Prov}_T(\ulcorner \delta \urcorner) \leftrightarrow \delta.$$

If it were provable, $\mathbf{T} \vdash \text{Prov}_T(\ulcorner \delta \urcorner)$ by condition (1), but the same conclusion follows if we apply modus ponens to the equivalence above. Hence, we don't get that \mathbf{T} is inconsistent, at least not by the same argument as in the case of the Gödel sentence. This of course does not show that \mathbf{T} *does* prove δ .

We can make headway on this question if we generalize it a bit. The left-to-right direction of the fixed point equivalence, $\text{Prov}_T(\ulcorner \delta \urcorner) \rightarrow \delta$, is an instance of a general schema called a *reflection principle*: $\text{Prov}_T(\ulcorner \varphi \urcorner) \rightarrow \varphi$. It is called that because it expresses, in a sense, that \mathbf{T} can “reflect” about what it can prove; basically it says, “If \mathbf{T} can prove φ , then φ is true,” for any φ . This is true for sound theories only, of course, and this suggests that theories will in general not prove every instance of it. So which instances can a theory (strong enough, and satisfying the provability conditions) prove? Certainly all those where φ itself is provable. And that's it, as the next result shows.

Theorem inp.1. *Let \mathbf{T} be an axiomatizable theory extending \mathbf{Q} , and suppose $\text{Prov}_T(y)$ is a formula satisfying conditions P1–P3 from ???. If \mathbf{T} proves $\text{Prov}_T(\ulcorner \varphi \urcorner) \rightarrow \varphi$, then in fact \mathbf{T} proves φ .*

Put differently, if $\mathbf{T} \not\vdash \varphi$, then $\mathbf{T} \not\vdash \text{Prov}_T(\ulcorner \varphi \urcorner) \rightarrow \varphi$. This result is known as Löb's theorem.

The heuristic for the proof of Löb's theorem is a clever proof that Santa Claus exists. (If you don't like that conclusion, you are free to substitute any other conclusion you would like.) Here it is: explanation

1. Let X be the sentence, “If X is true, then Santa Claus exists.”
2. Suppose X is true.
3. Then what it says holds; i.e., we have: if X is true, then Santa Claus exists.
4. Since we are assuming X is true, we can conclude that Santa Claus exists, by modus ponens from (2) and (3).
5. We have succeeded in deriving (4), “Santa Claus exists,” from the assumption (2), “ X is true.” By conditional proof, we have shown: “If X is true, then Santa Claus exists.”

6. But this is just the sentence X . So we have shown that X is true.

7. But then, by the argument (2)–(4) above, Santa Claus exists.

A formalization of this idea, replacing “is true” with “is provable,” and “Santa Claus exists” with φ , yields the proof of Löb’s theorem. The trick is to apply the fixed-point lemma to the formula $\text{Prov}_T(y) \rightarrow \varphi$. The fixed point of that corresponds to the sentence X in the preceding sketch.

Proof. Suppose φ is a sentence such that \mathbf{T} proves $\text{Prov}_T(\ulcorner \varphi \urcorner) \rightarrow \varphi$. Let $\psi(y)$ be the formula $\text{Prov}_T(y) \rightarrow \varphi$, and use the fixed-point lemma to find a sentence θ such that \mathbf{T} proves $\theta \leftrightarrow \psi(\ulcorner \theta \urcorner)$. Then each of the following is provable in \mathbf{T} :

- | | |
|---|---|
| $\theta \leftrightarrow (\text{Prov}_T(\ulcorner \theta \urcorner) \rightarrow \varphi)$ | (1) <small>inc:inp:lob:
L-1</small> |
| θ is a fixed point of $\psi(y)$ | |
| $\theta \rightarrow (\text{Prov}_T(\ulcorner \theta \urcorner) \rightarrow \varphi)$ | (2) <small>inc:inp:lob:
L-2</small> |
| from eq. (1) | |
| $\text{Prov}_T(\ulcorner \theta \rightarrow (\text{Prov}_T(\ulcorner \theta \urcorner) \rightarrow \varphi) \urcorner)$ | (3) <small>inc:inp:lob:
L-3</small> |
| from eq. (2) by condition P1 | |
| $\text{Prov}_T(\ulcorner \theta \urcorner) \rightarrow \text{Prov}_T(\ulcorner \text{Prov}_T(\ulcorner \theta \urcorner) \rightarrow \varphi \urcorner)$ | (4) <small>inc:inp:lob:
L-4</small> |
| from eq. (3) using condition P2 | |
| $\text{Prov}_T(\ulcorner \theta \urcorner) \rightarrow (\text{Prov}_T(\ulcorner \text{Prov}_T(\ulcorner \theta \urcorner) \urcorner) \rightarrow \text{Prov}_T(\ulcorner \varphi \urcorner))$ | (5) <small>inc:inp:lob:
L-5</small> |
| from eq. (4) using P2 again | |
| $\text{Prov}_T(\ulcorner \theta \urcorner) \rightarrow \text{Prov}_T(\ulcorner \text{Prov}_T(\ulcorner \theta \urcorner) \urcorner)$ | (6) <small>inc:inp:lob:
L-6</small> |
| by provability condition P3 | |
| $\text{Prov}_T(\ulcorner \theta \urcorner) \rightarrow \text{Prov}_T(\ulcorner \varphi \urcorner)$ | (7) <small>inc:inp:lob:
L-7</small> |
| from eq. (5) and eq. (6) | |
| $\text{Prov}_T(\ulcorner \varphi \urcorner) \rightarrow \varphi$ | (8) <small>inc:inp:lob:
L-8</small> |
| by assumption of the theorem | |
| $\text{Prov}_T(\ulcorner \theta \urcorner) \rightarrow \varphi$ | (9) <small>inc:inp:lob:
L-9</small> |
| from eq. (7) and eq. (8) | |
| $(\text{Prov}_T(\ulcorner \theta \urcorner) \rightarrow \varphi) \rightarrow \theta$ | (10) <small>inc:inp:lob:
L-10</small> |
| from eq. (1) | |
| θ | (11) <small>inc:inp:lob:
L-11</small> |
| from eq. (9) and eq. (10) | |
| $\text{Prov}_T(\ulcorner \theta \urcorner)$ | (12) <small>inc:inp:lob:
L-12</small> |
| from eq. (11) by condition P1 | |
| φ | from eq. (8) and eq. (12) |

□

With Löb's theorem in hand, there is a short proof of the first incompleteness theorem (for theories having a provability predicate satisfying conditions P1–P3: if $\mathbf{T} \vdash \text{Prov}_T(\ulcorner \perp \urcorner) \rightarrow \perp$, then $\mathbf{T} \vdash \perp$. If \mathbf{T} is consistent, $\mathbf{T} \not\vdash \perp$. So, $\mathbf{T} \not\vdash \text{Prov}_T(\ulcorner \perp \urcorner) \rightarrow \perp$, i.e., $\mathbf{T} \not\vdash \text{Con}_{\mathbf{T}}$. We can also apply it to show that δ , the fixed point of $\text{Prov}_T(x)$, is provable. For since

$$\mathbf{T} \vdash \text{Prov}_T(\ulcorner \delta \urcorner) \leftrightarrow \delta$$

in particular

$$\mathbf{T} \vdash \text{Prov}_T(\ulcorner \delta \urcorner) \rightarrow \delta$$

and so by Löb's theorem, $\mathbf{T} \vdash \delta$.

Problem inp.1. Let \mathbf{T} be a computably axiomatized theory, and let Prov_T be a provability predicate for \mathbf{T} . Consider the following four statements:

1. If $T \vdash \varphi$, then $T \vdash \text{Prov}_T(\ulcorner \varphi \urcorner)$.
2. $T \vdash \varphi \rightarrow \text{Prov}_T(\ulcorner \varphi \urcorner)$.
3. If $T \vdash \text{Prov}_T(\ulcorner \varphi \urcorner)$, then $T \vdash \varphi$.
4. $T \vdash \text{Prov}_T(\ulcorner \varphi \urcorner) \rightarrow \varphi$

Under what conditions are each of these statements true?

Photo Credits

Bibliography