

thy.1 The Normal Form Theorem

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thm.normal-form

Theorem thy.1 (Kleene’s Normal Form Theorem). *There are a primitive recursive relation $T(k, x, s)$ and a primitive recursive function $U(s)$, with the following property: if f is any partial computable function, then for some k ,*

$$f(x) \simeq U(\mu s T(k, x, s))$$

for every x .

Proof Sketch. For any model of computation one can rigorously define a description of the computable function f and code such description using a natural number k . One can also rigorously define a notion of “computation sequence” which records the process of computing the function with index k for input x . These computation sequences can likewise be coded as numbers s . This can be done in such a way that (a) it is decidable whether a number s codes the computation sequence of the function with index k on input x and (b) what the end result of the computation sequence coded by s is. In fact, the relation in (a) and the function in (b) are primitive recursive. \square

In order to give a rigorous proof of the Normal Form Theorem, we would have to fix a model of computation and carry out the coding of descriptions of computable functions and of computation sequences in detail, and verify that the relation T and function U are primitive recursive. For most applications, it suffices that T and U are computable and that U is total. explanation

It is probably best to remember the proof of the normal form theorem in slogan form: $\mu s T(k, x, s)$ searches for a computation sequence of the function with index k on input x , and U returns the output of the computation sequence if one can be found.

T and U can be used to define the enumeration $\varphi_0, \varphi_1, \varphi_2, \dots$. From now on, we will assume that we have fixed a suitable choice of T and U , and take the equation

$$\varphi_e(x) \simeq U(\mu s T(e, x, s))$$

to be the *definition* of φ_e .

Here is another useful fact:

Theorem thy.2. *Every partial computable function has infinitely many indices.*

Again, this is intuitively clear. Given any (description of) a computable function, one can come up with a different description which computes the same function (input-output pair) but does so, e.g., by first doing something that has no effect on the computation (say, test if $0 = 0$, or count to 5, etc.). The index of the altered description will always be different from the original index. Both are indices of the same function, just computed slightly differently.

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Bibliography